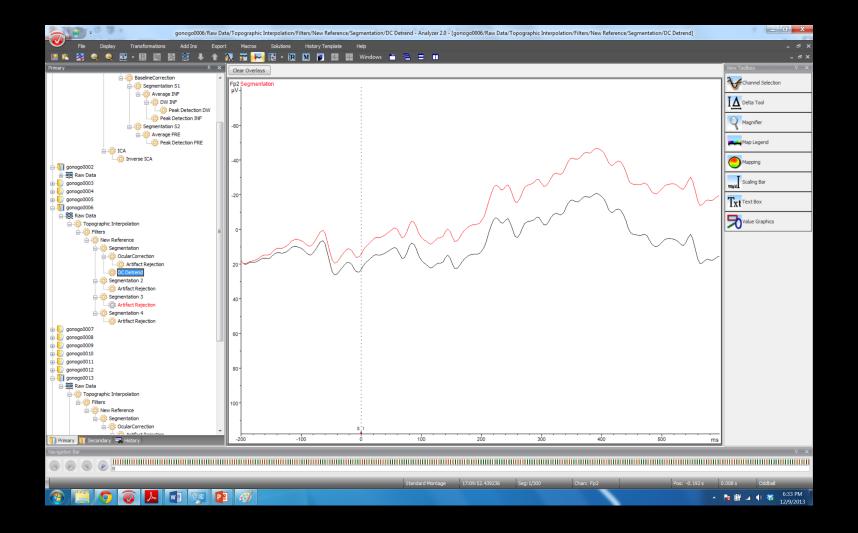
Some other things to consider...

DC Detrend (optional)

DC Detrend

Removes a continuous DC slope from each segment.

Note, this step, if used, should be done before ocular correction.



DC Detrend Demo

Most of these steps are linear – they can be interchanged.

For instance, if you are using gradient and maxmin criteria for artifact rejection then it does not matter if it comes before or after baseline correction.

There are some exceptions...

Rereference

Always reference on continuous data as soon as possible.

Filtering

Always filter continuous data to avoid edge artifacts.

DC Detrend

Must be done before ocular correction.

Ocular Correction

Should be done as early as possible after segmentation and before artifact rejection.

Channel Interpolation

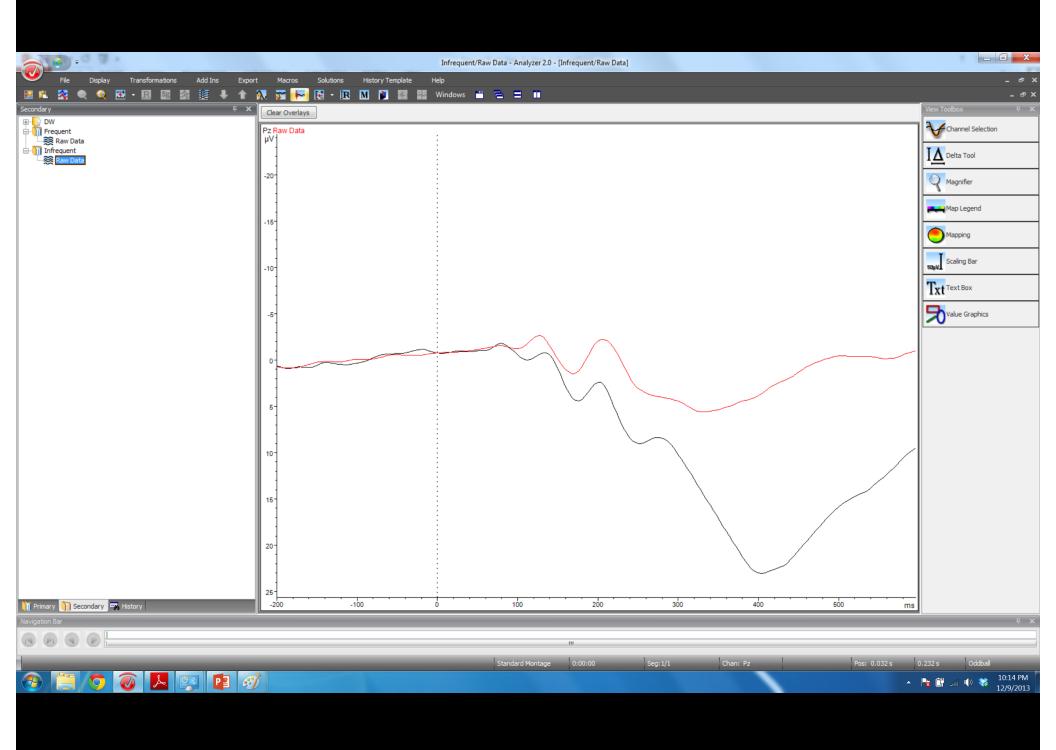
Always interpolate bad channels after ocular correction but before artifact rejection.

Session 4 Data Analysis I

Grand Averages

Grand Averages

The notion of a grand average waveform is very simple – average together all of the conditional waveforms for each participant to get a "grand average" for each condition.



But don't forget...

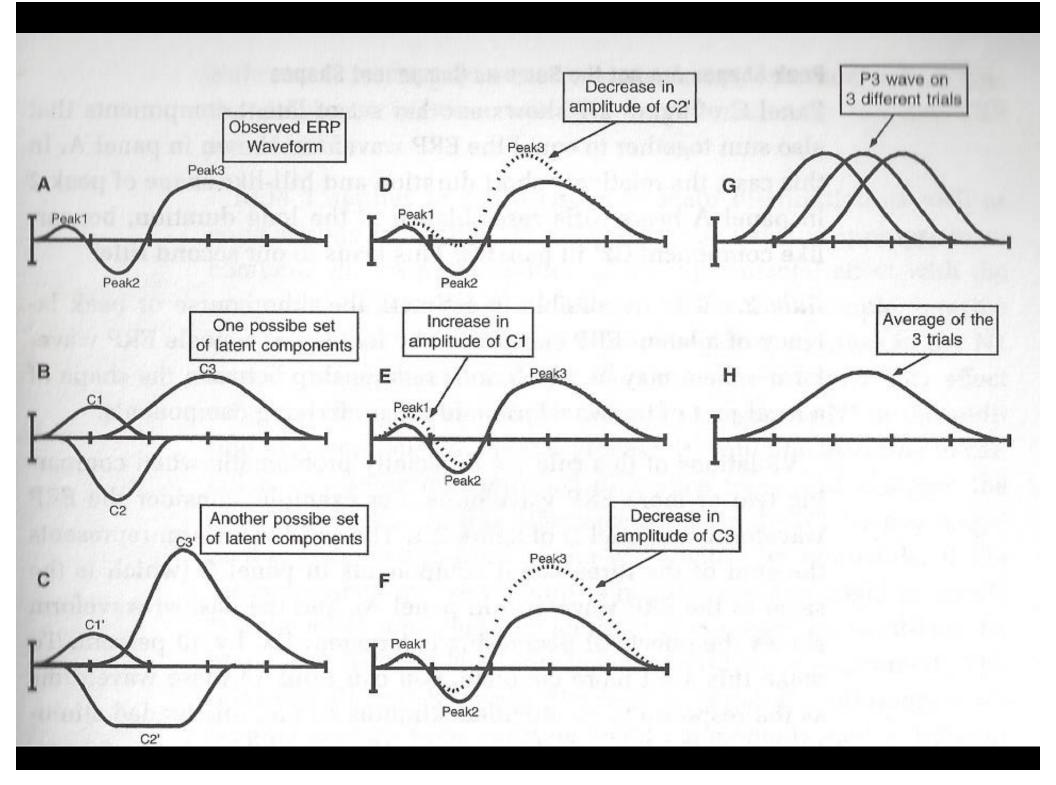
"There is nothing special about the point in time a grand average waveform reaches a maxima or minima – this may have not reveal the true nature of the underlying components."

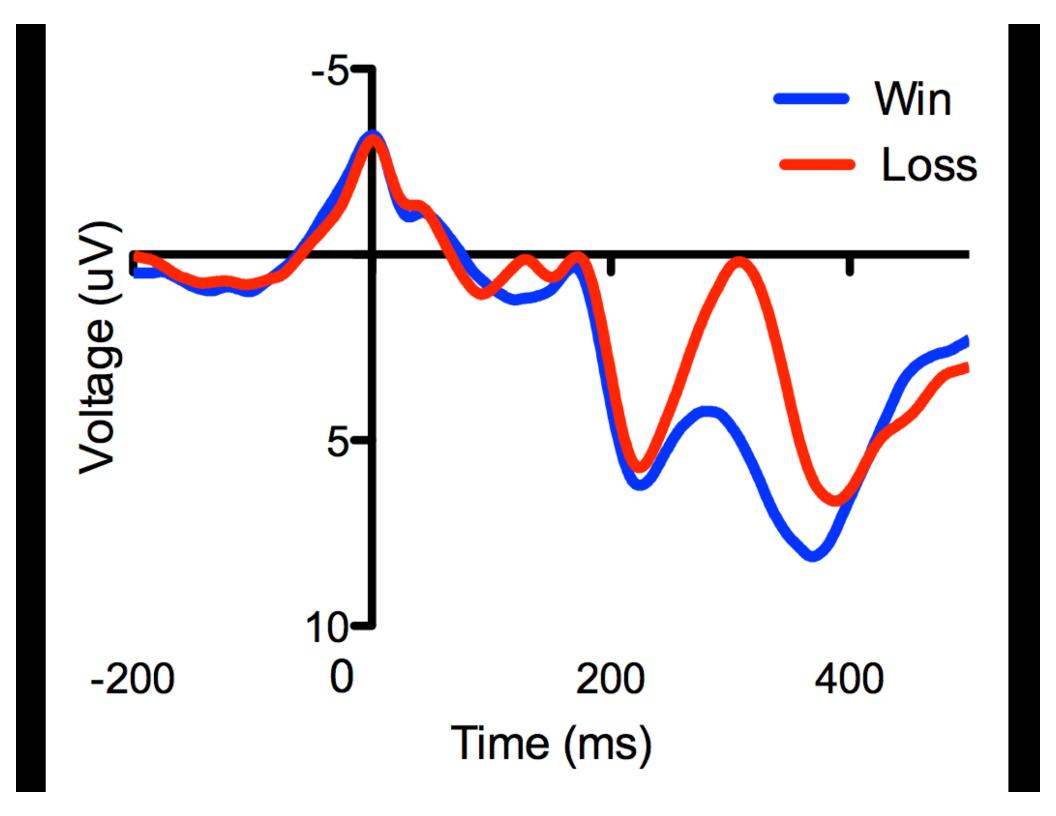
Things to check...

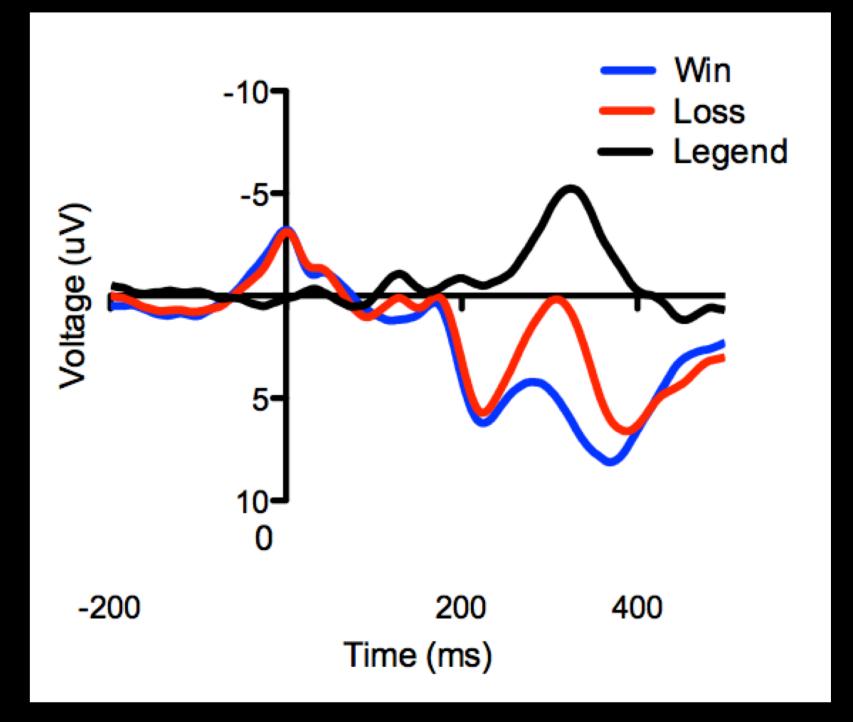
This is a good time to check:

- 1. The number of blink trials for each participant for each condition (i.e., systematic blinking)
- The number of artefact trials for each participant for each condition again systematic effects.
- 3. To review individual participants waveforms to see the contribution of each or the similarity of each to the grand average.

Difference Waveforms







Difference Waveforms

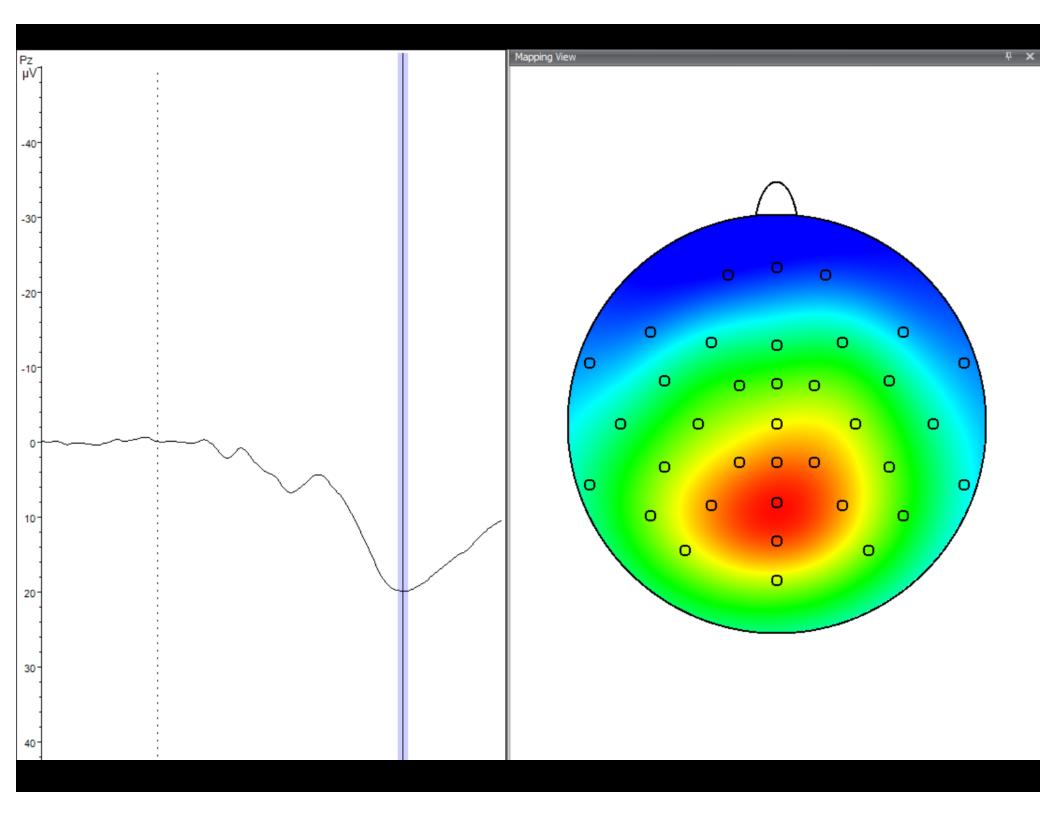
Whenever possible, you should construct difference waveforms for subsequent analysis.

You need to do this for each participant, although the grand average difference waveform will show the effects. You need the participant difference waveforms to get numbers for statistics.

The topography of a component is important to verify that is indeed a "typical" component.

For instance, we expect the P300 to have a posterior topography with a positivity maximal at Pz for an Oddball Task.

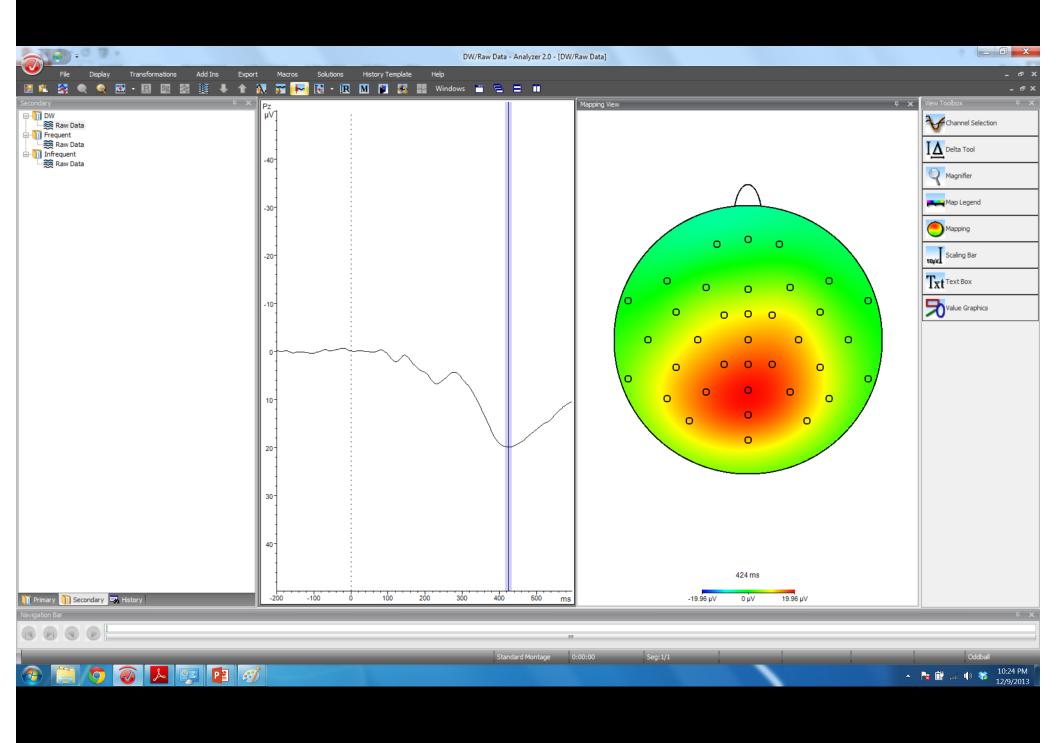
But...



Interpreting topographies can be tricky.

Some pitfalls...

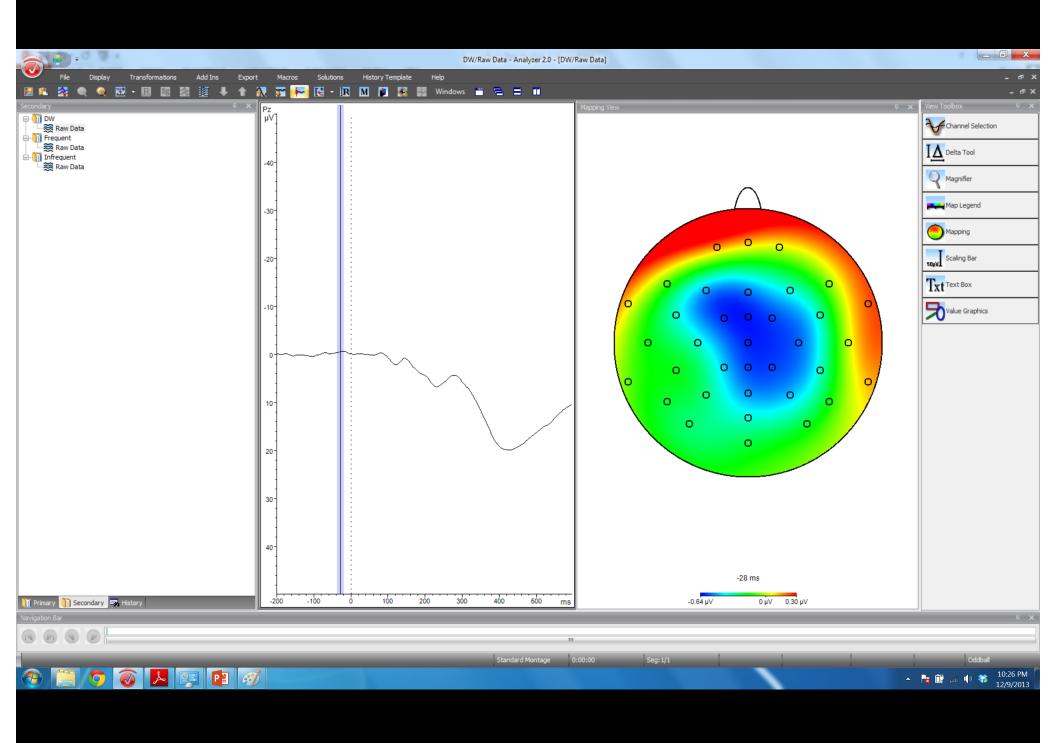
1. Symmetric scaling may distort the topography.

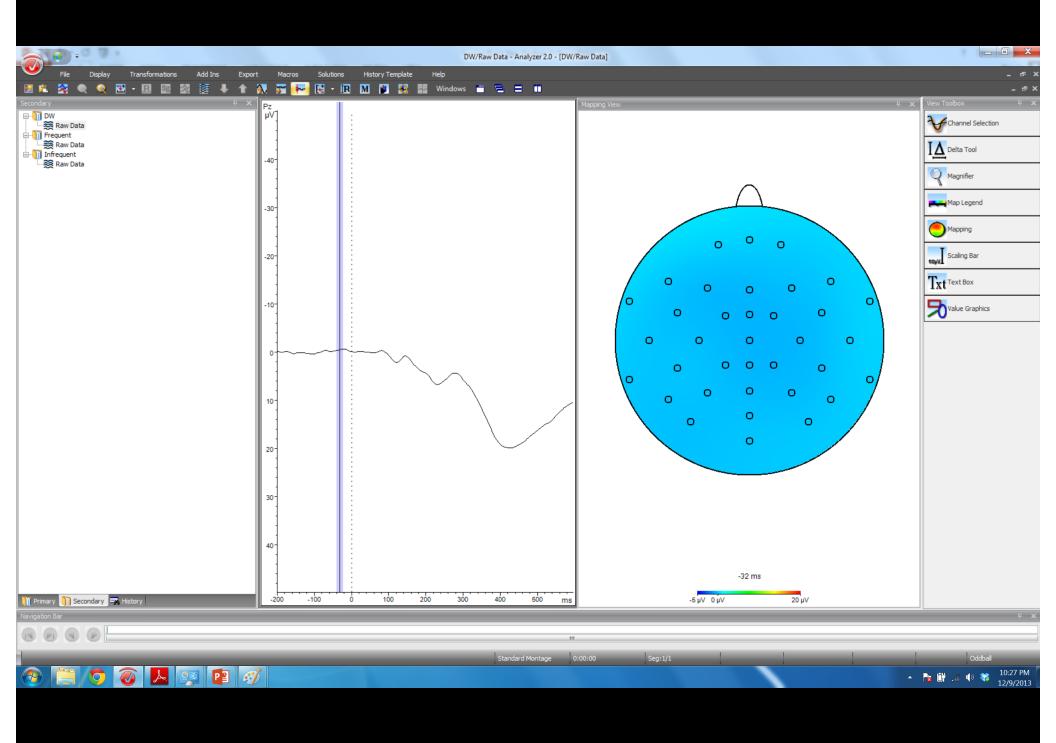


Interpreting topographies can be tricky.

Some pitfalls...

2. Autoscaling may make it look like there is something when there is not.

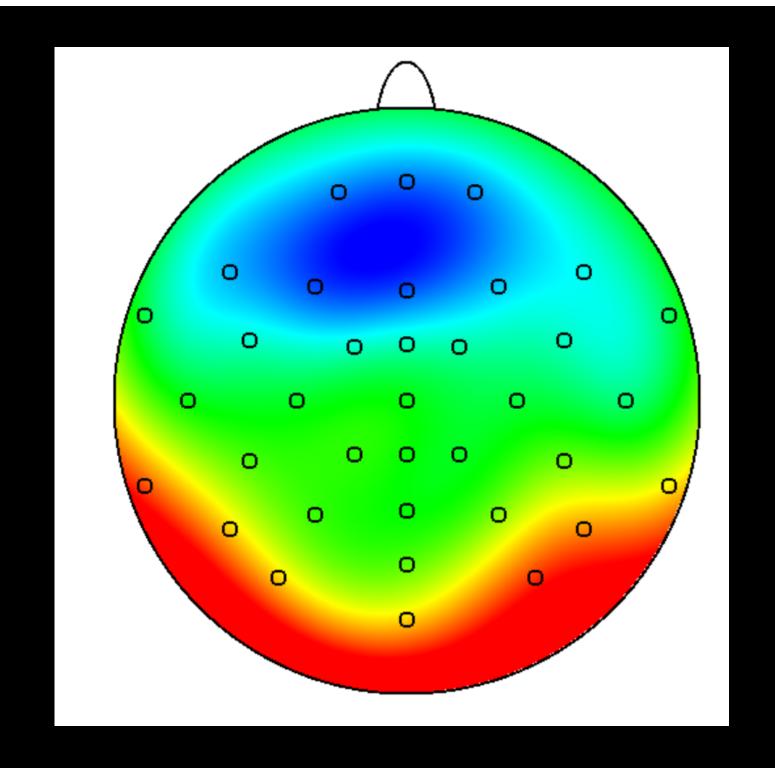




Interpreting topographies can be tricky.

Some pitfalls...

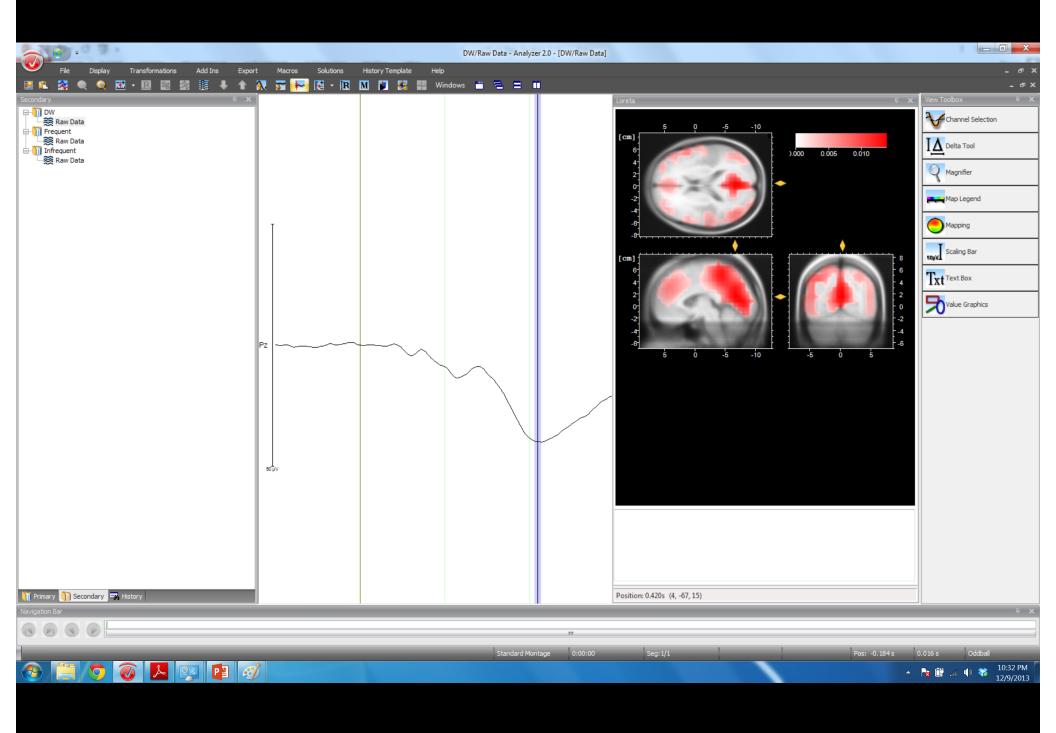
3. Keep an out for dipoles.



Interpreting topographies can be tricky.

Some pitfalls...

4. Don't get caught up in Loreta...



A Final Note

The topography of interest is actually not the topography of the grand average difference waveform – it is the topography of the peak detection process.

We till talk about this in a bit...

Quantifying Components: Peak Detection

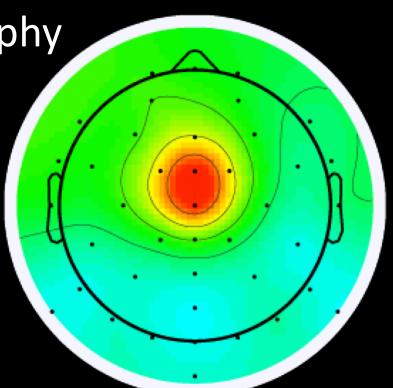
Component Definition

ERP Components have:

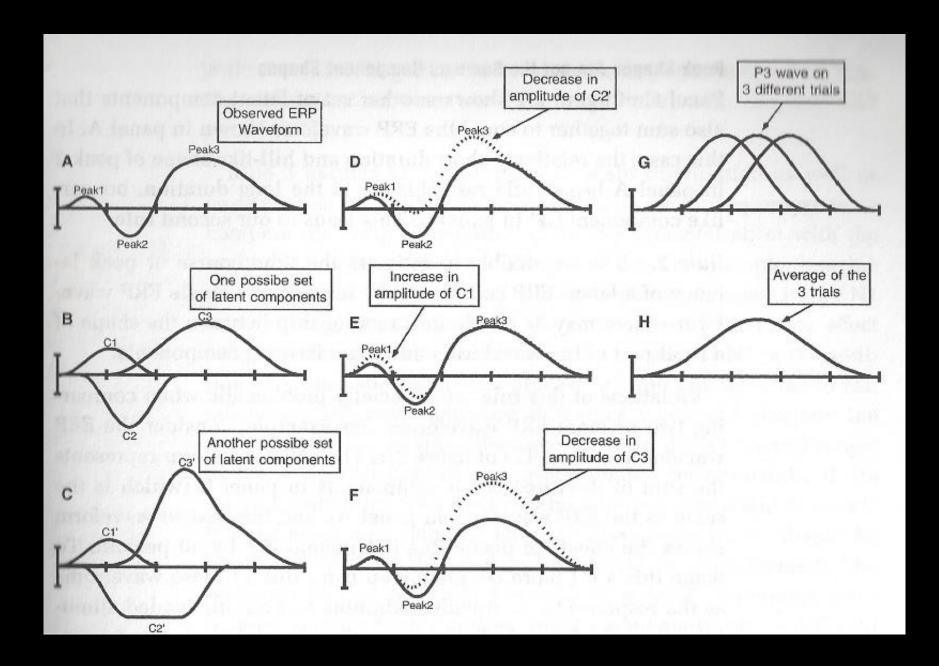
A Polarity (e.g., N200, P300)

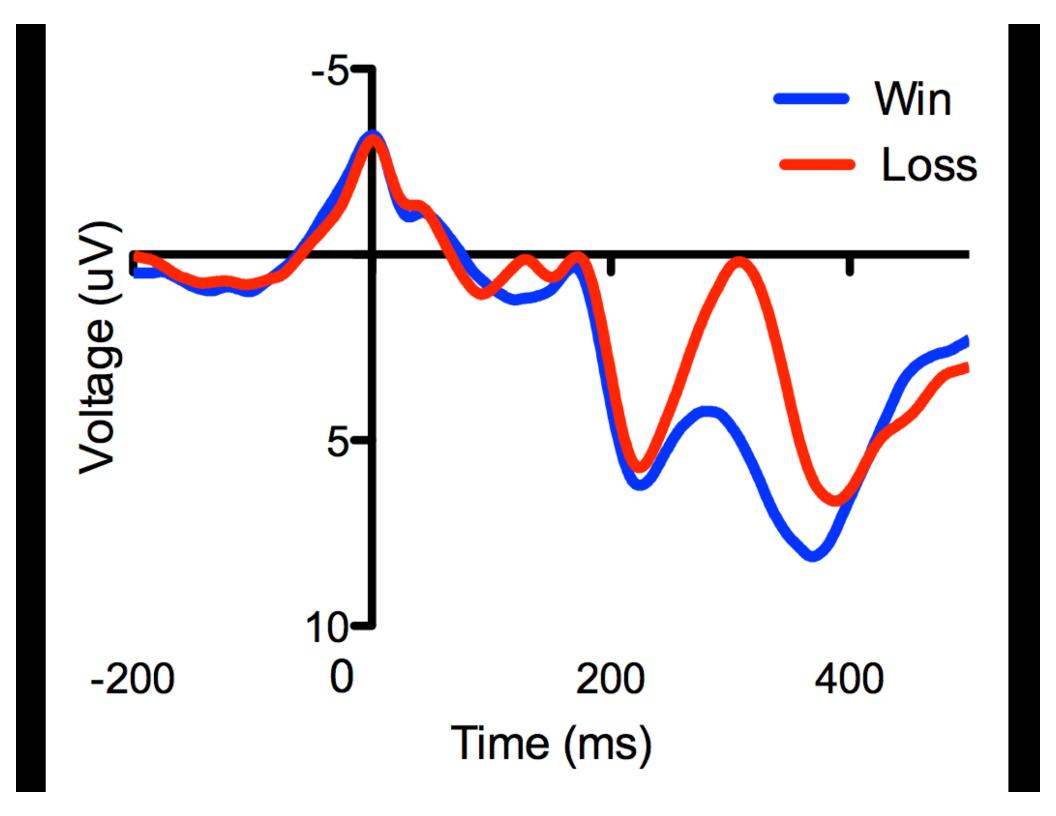
A Timing (e.g., 200 to 300 ms)

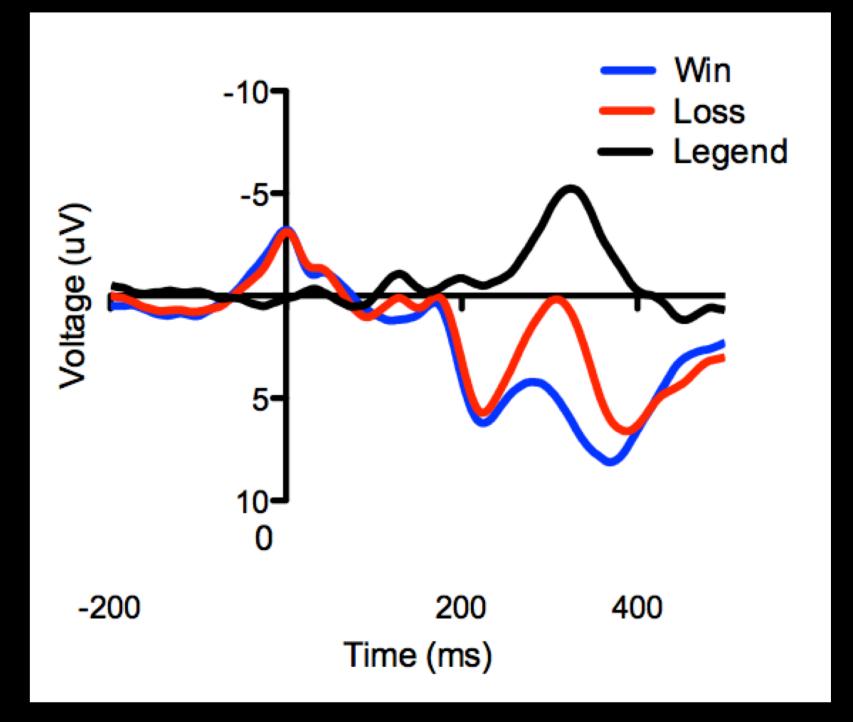
A Scalp Topography



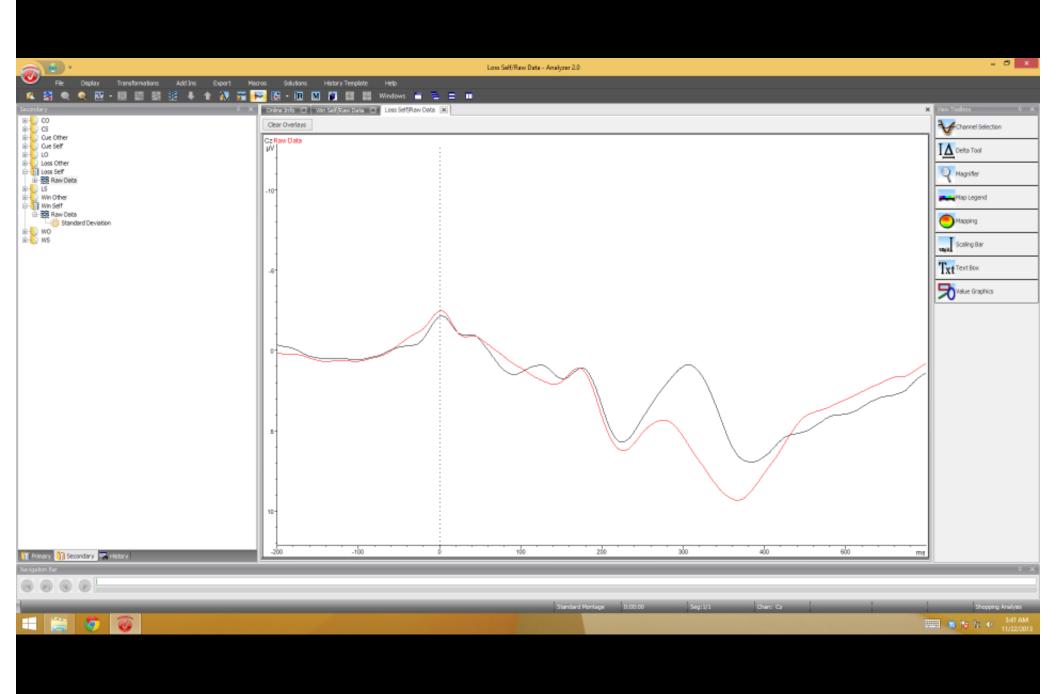
Conditional Waveforms?

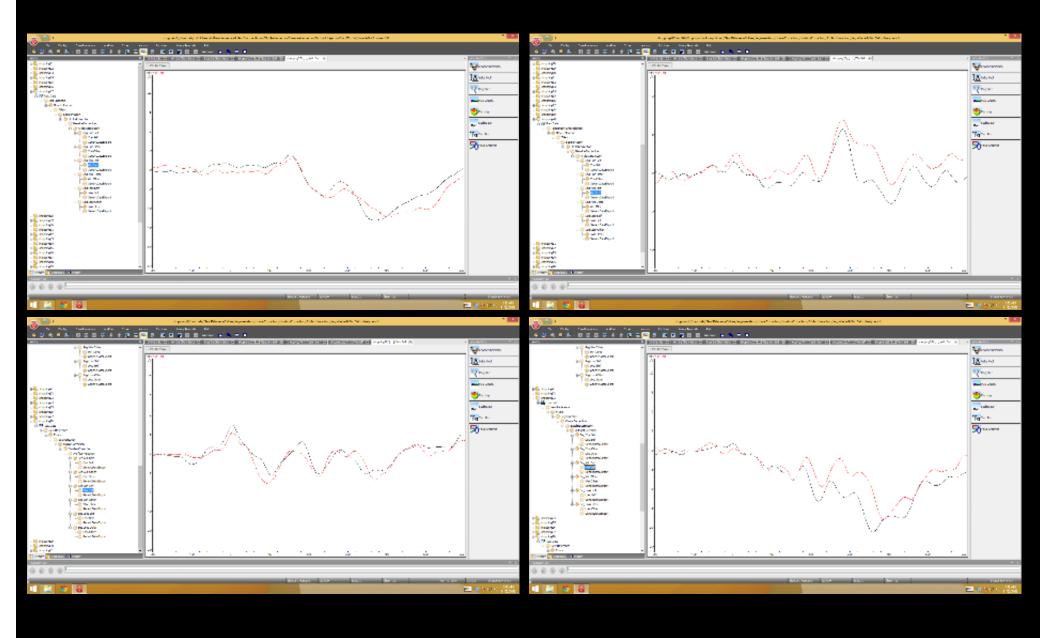






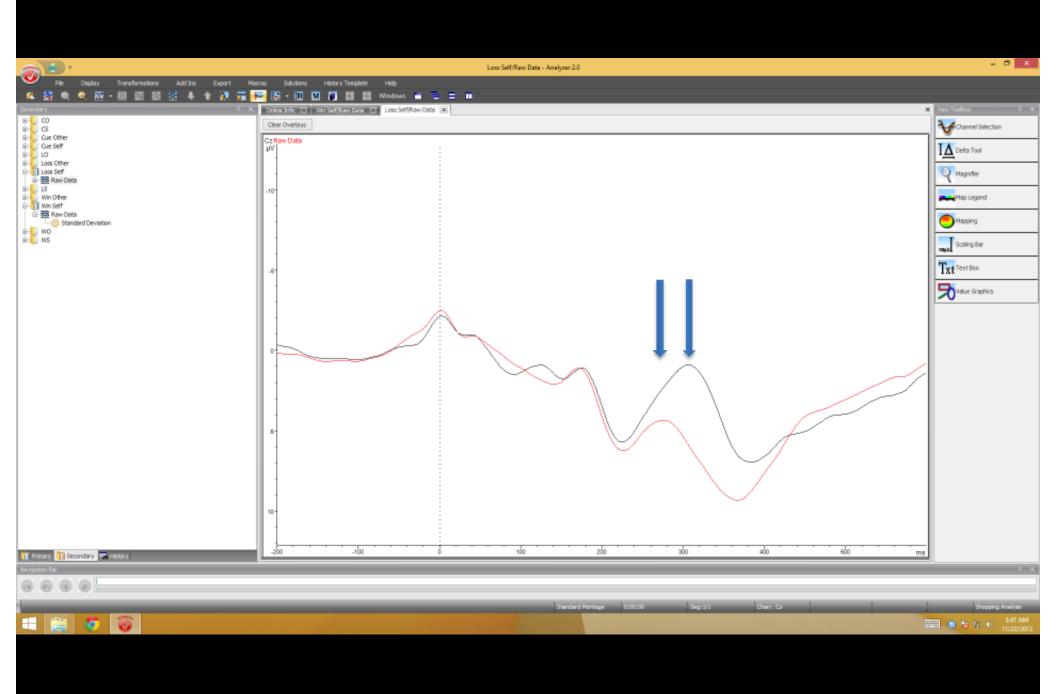
Subject or Grand Averages

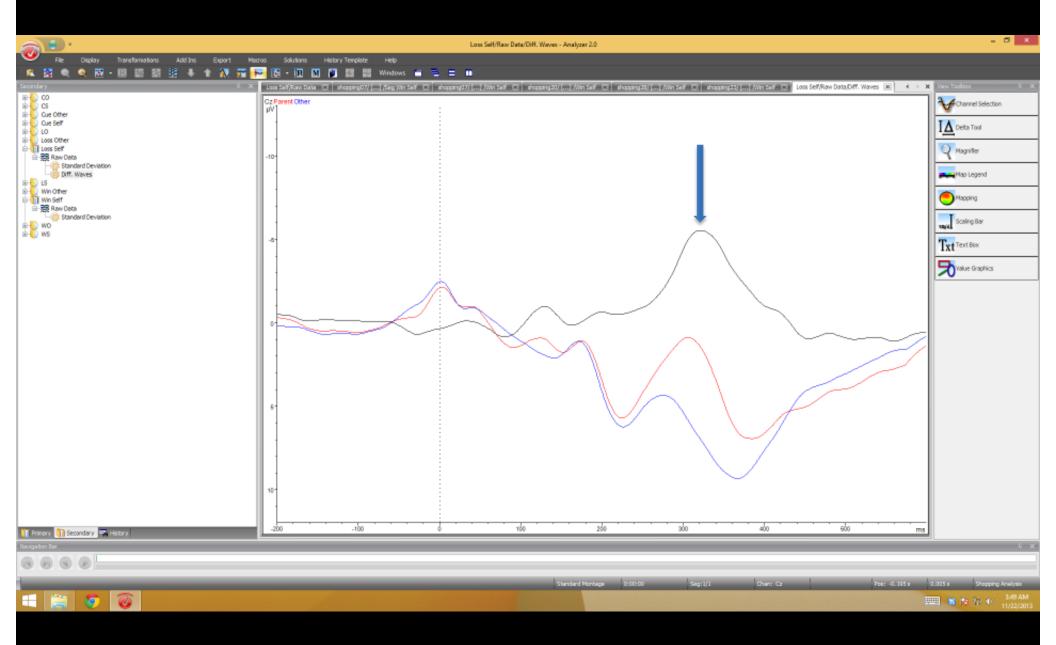




So, we base the "timing" of the component on either the GRAND AVERAGE WAVEFORM or APRIORI KNOWLEDGE

e.g., The P300 "lives" between 300 and 600 ms post stimulus onset based on the literature...
BUT... what is the problem with this...



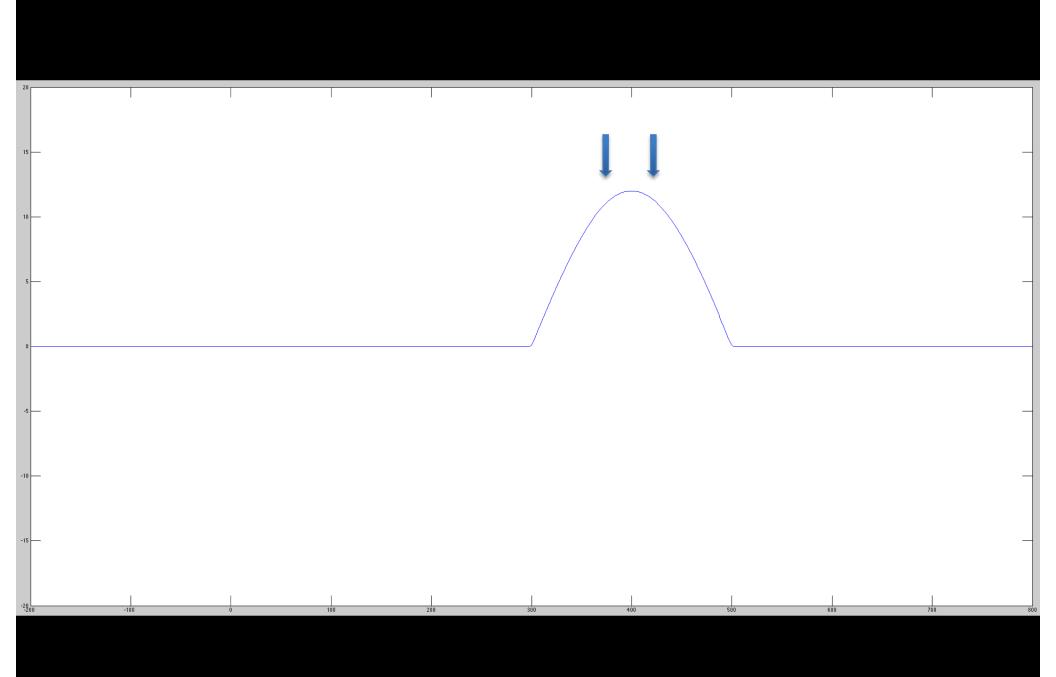


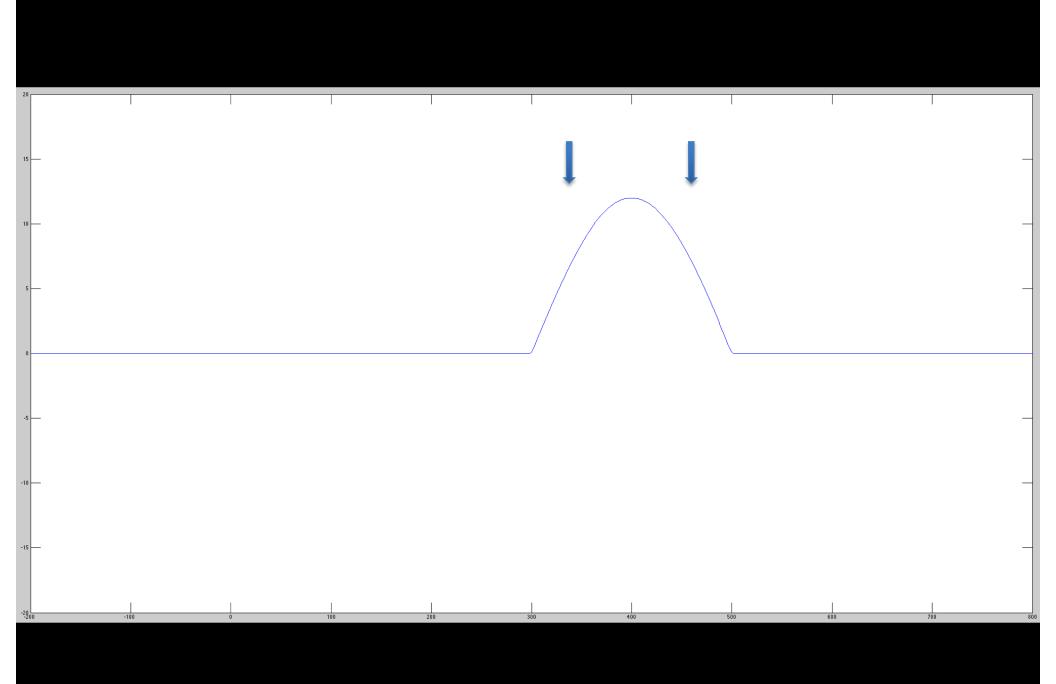
Mean Peak Measures

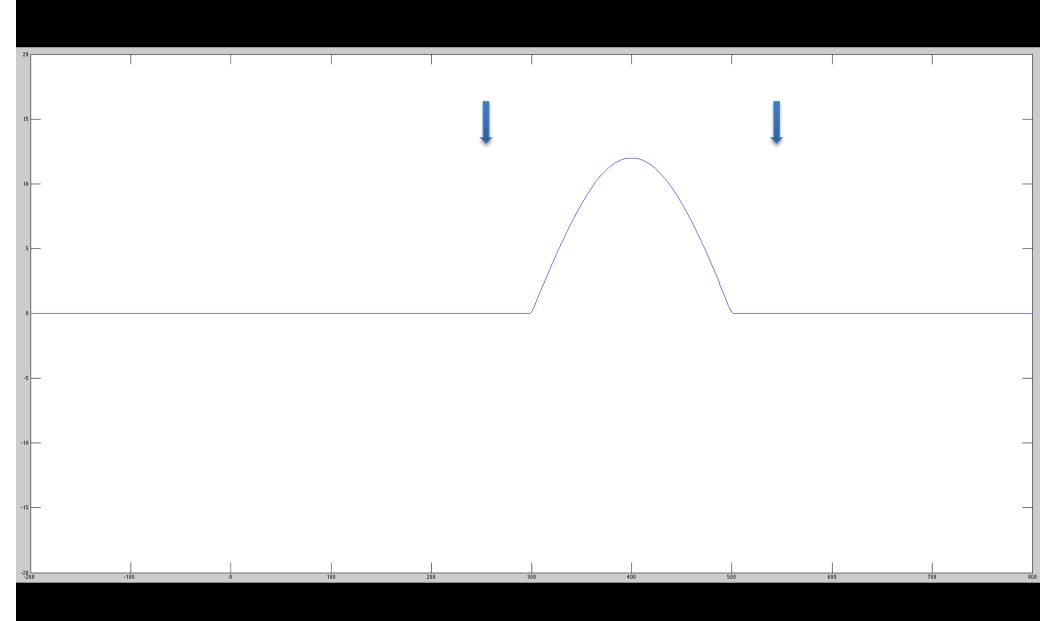
It is worth noting that some researchers base the timing of their component on absolute time points – i.e., "I will use the mean from 200 to 300 ms"... to be fair, I have done this myself. But, WHY??? Do the underlying components really care about discrete time bins?

But the idea is simple, a mean peak is simply the mean voltage over a time window.

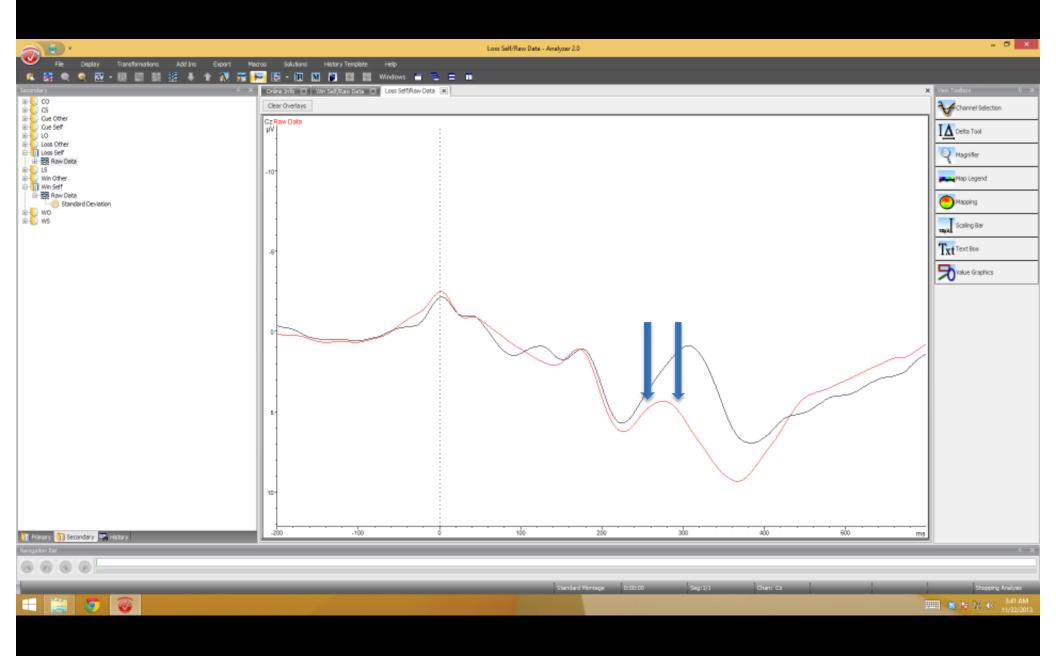
Mean Window Width

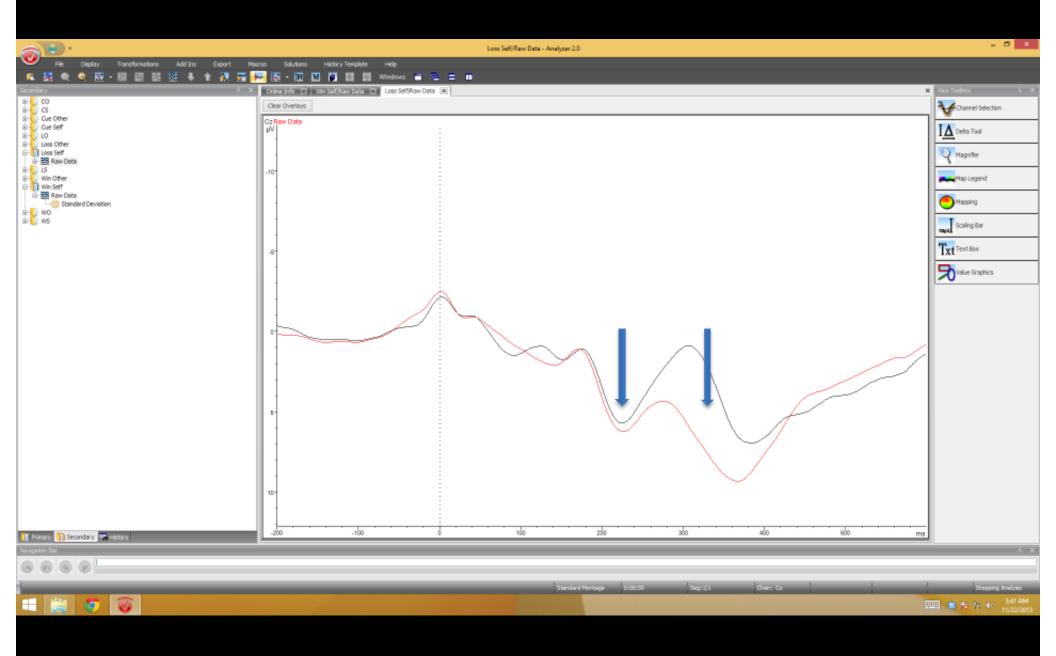


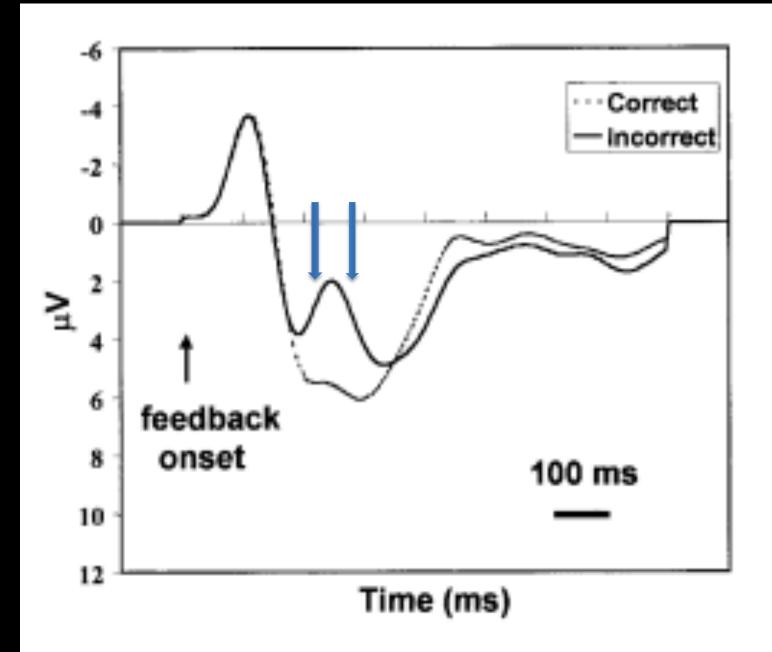


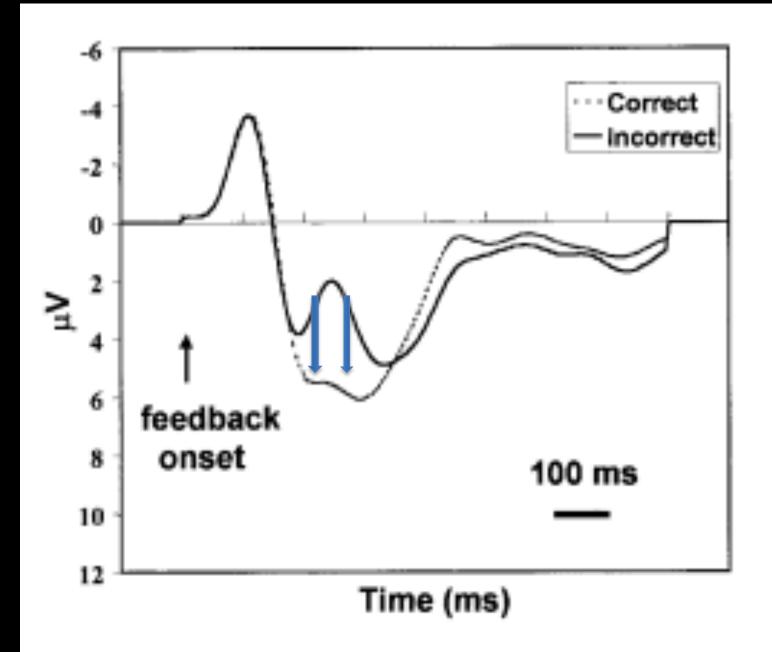


What is the trend in the components amplitude?





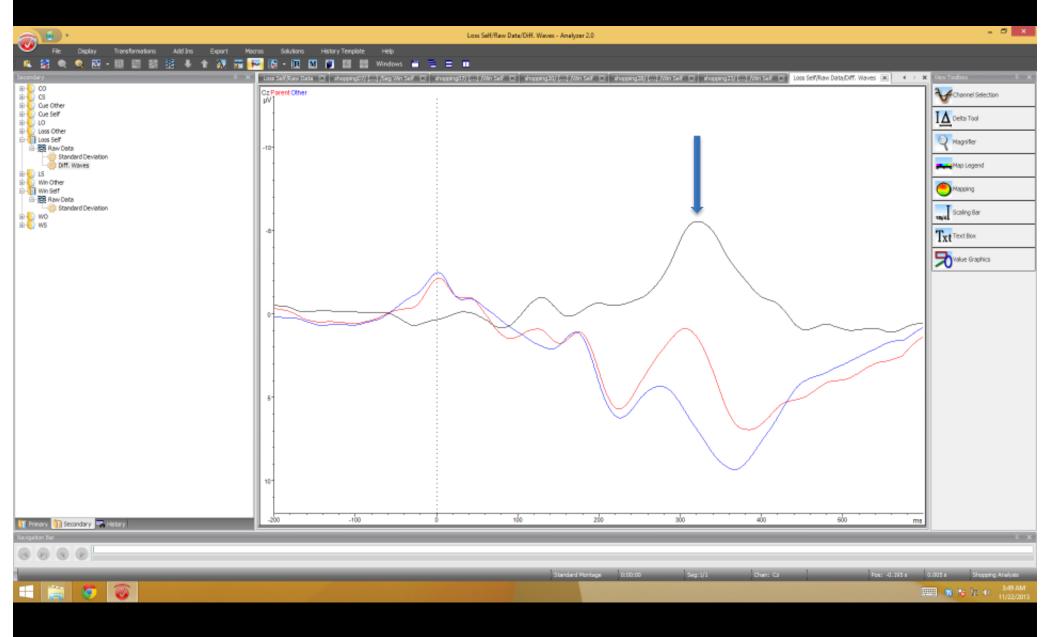




So, we use a WINDOW based on the grand average that we "hope" captures a mean voltage for each participant that measures the component of interest.

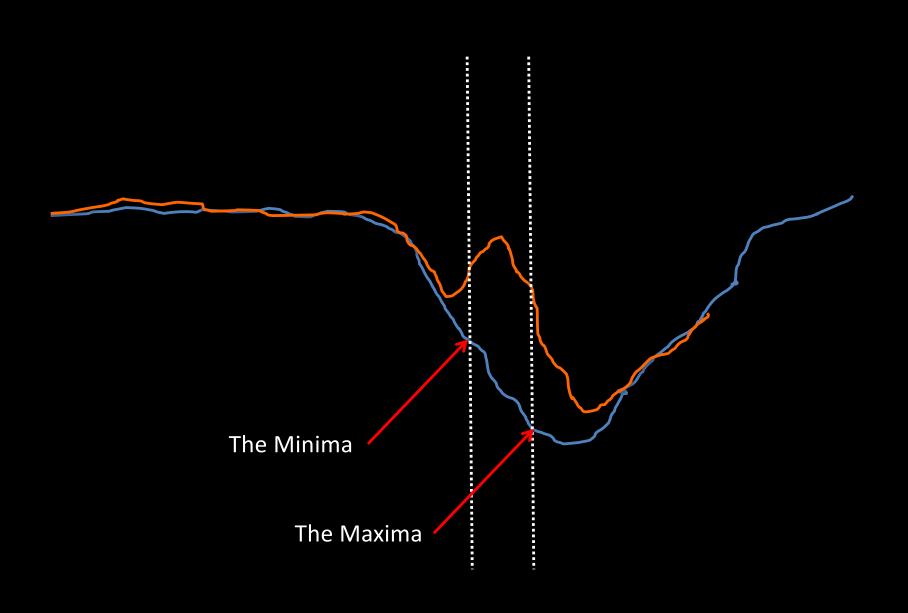
WINDOW WIDTH? Hard to have an absolute value. We can use prior research to guide us.

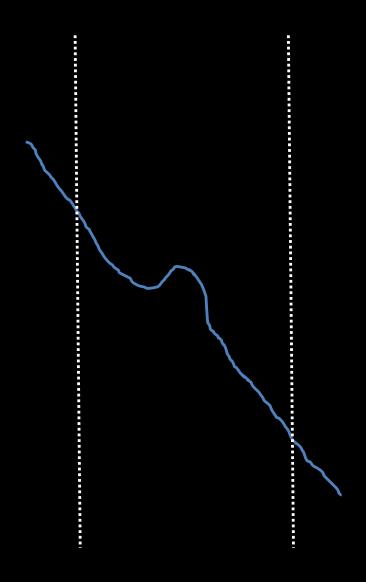
Peak Measures



Simply put, we search for a maxima or a minima depending on the component.

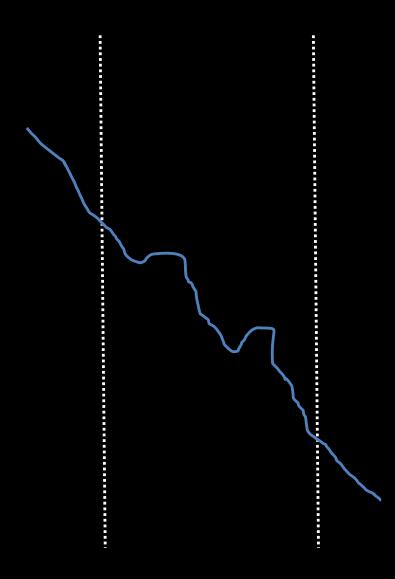
But there are many problems...





This would be a problem for a GLOBAL search, but not a LOCAL search.

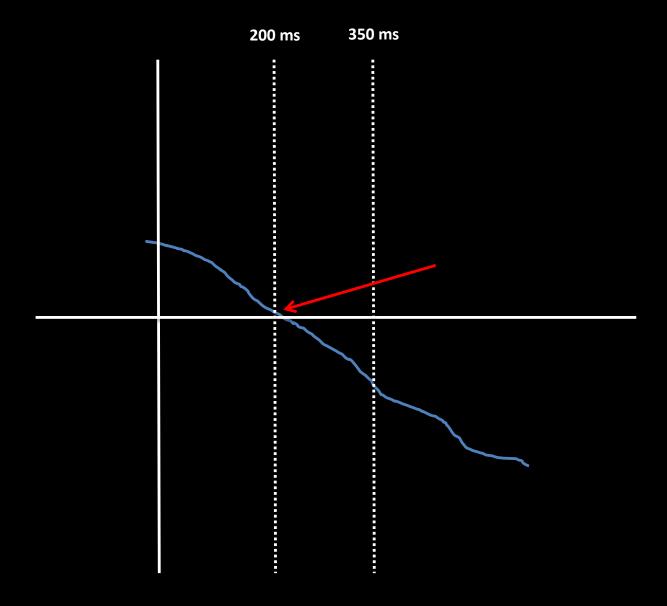
A LOCAL search defines a start and end time then looks for the first reversal and then a subsequent one to find this peak.



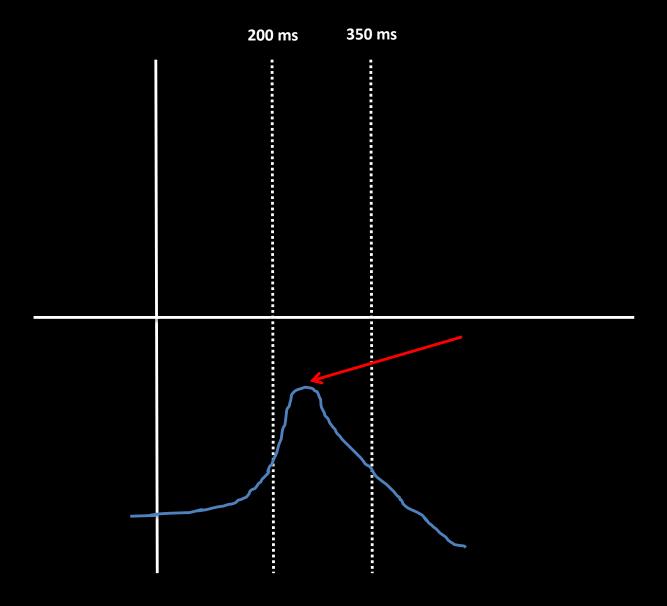
But this still would be a problem.

Subject	Peak	Latency
1	-4.56	214
2	-1.23	256
3	-0.12	200
4	2.43	278
5	-5.67	244
6	-11.23	321
7	-4.11	350

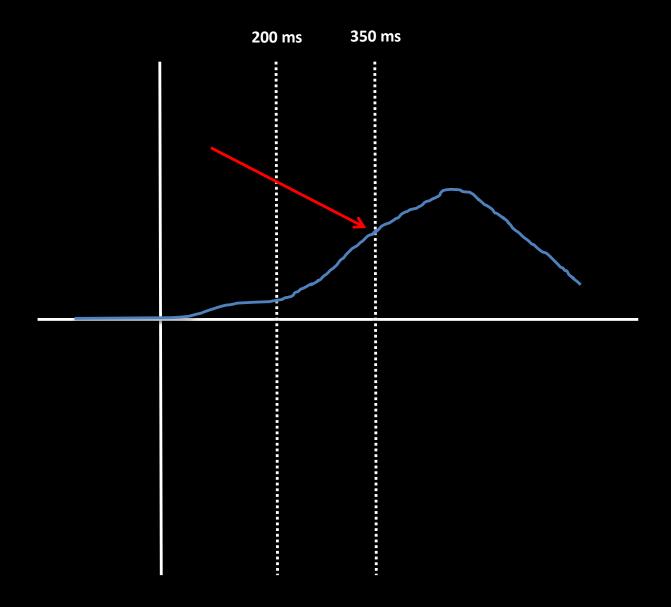
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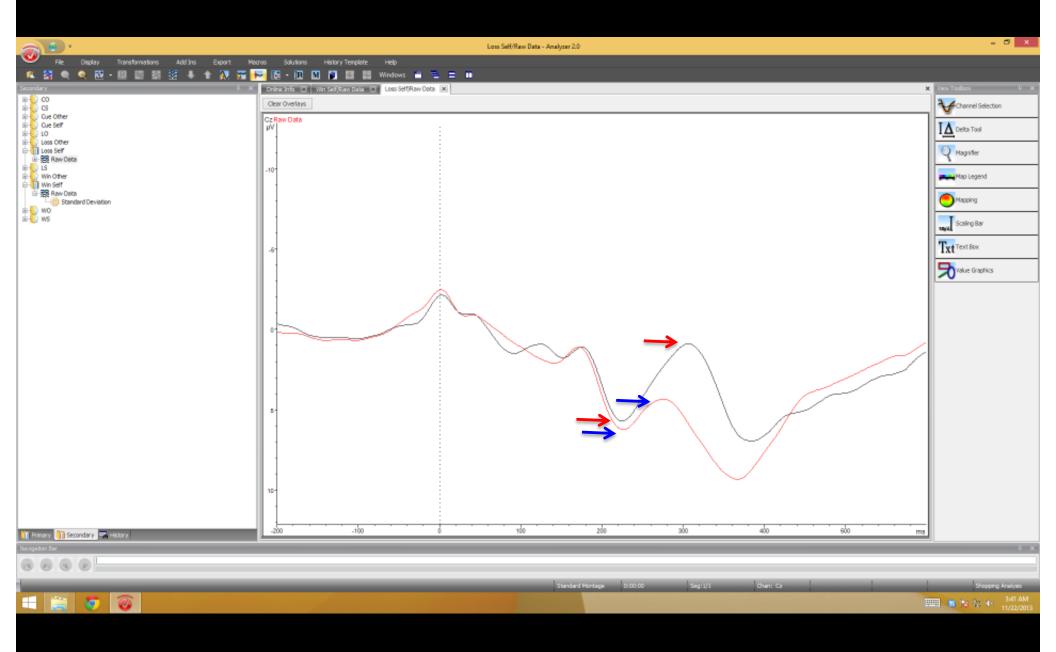


Peak Differences

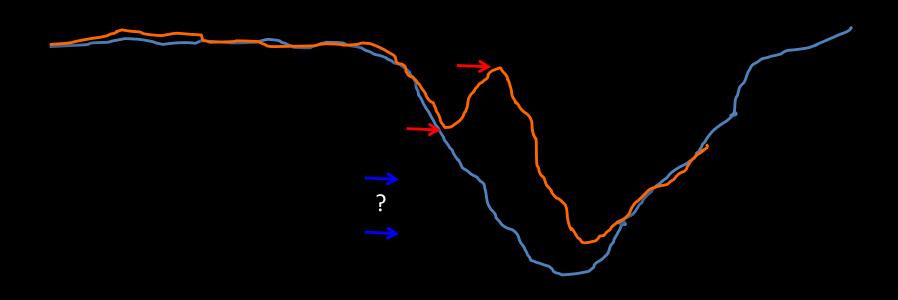
It should be worth noting there is nothing special about the peak amplitude difference.

Recall, we are interested in underlying components. Just because we use difference waveforms does not mean that the underlying component is isolated – thus – the "peak difference" may not reflect what we think it does.

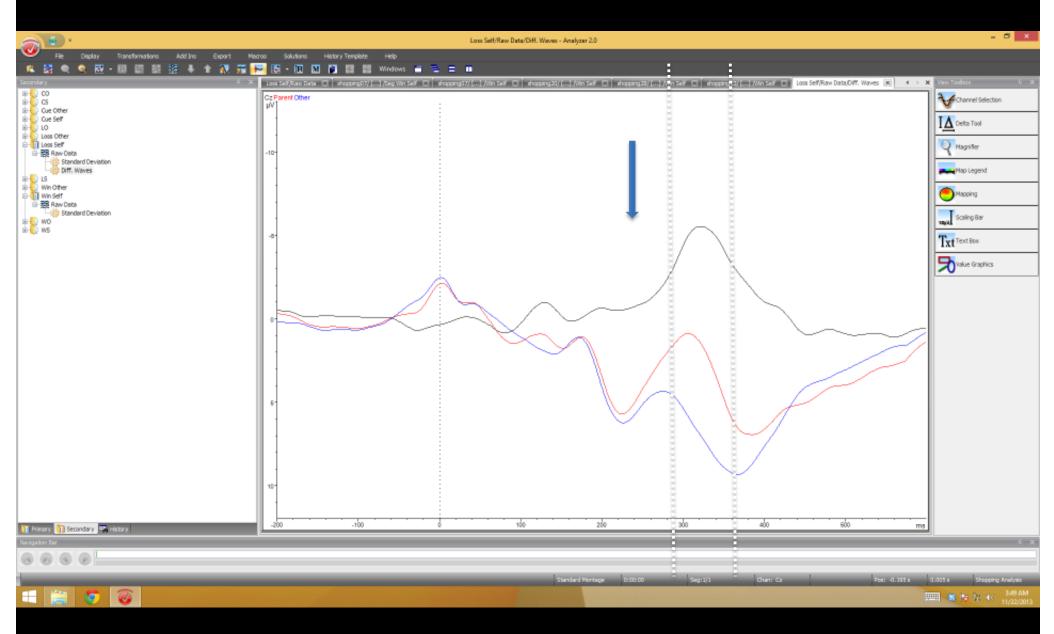
Base to Peak Measures



So, what are the problems?



Other Thoughts...



What happens if a subject's peak lies outside this region? NOTE: This is a problem for mean measures too.

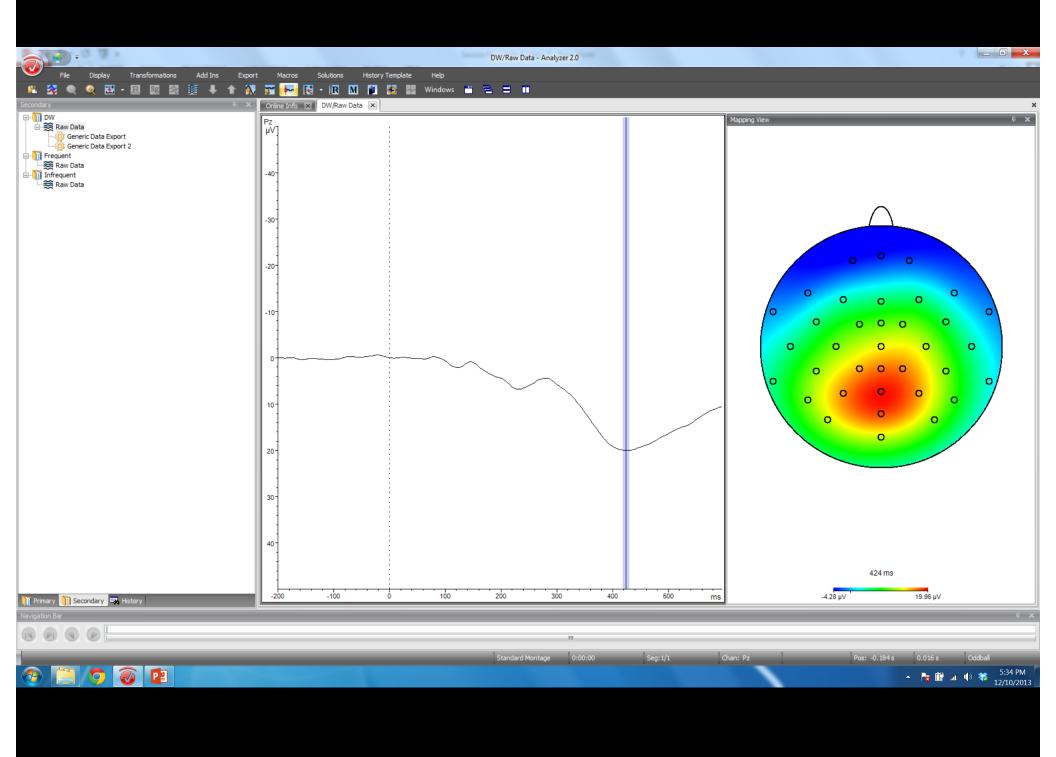
So in sum...

- 1. Create a difference waveform for each subject
- 2. Create a grand average difference waveform
- 3. Get the peak latency of the component from the grand average difference waveform
- 4. Use a mean centered around this window
- 5. Generate a topography from the peak detection (hard to do in BV) to verify the component

Topography Quantification

Grand Average Topographies

Simply put, this is the topography of the grand average peak difference (or conditional maxima or minima).



Grand Average Topographies

What is this useful for?

Determining where to run your peak detection (but not peak verification)

How do you get values?

Data Export (next section)

Peak Topographies

If you are going to use mean peak detection, then the individual peak topography matches the grand average topography.

Peak Topographies

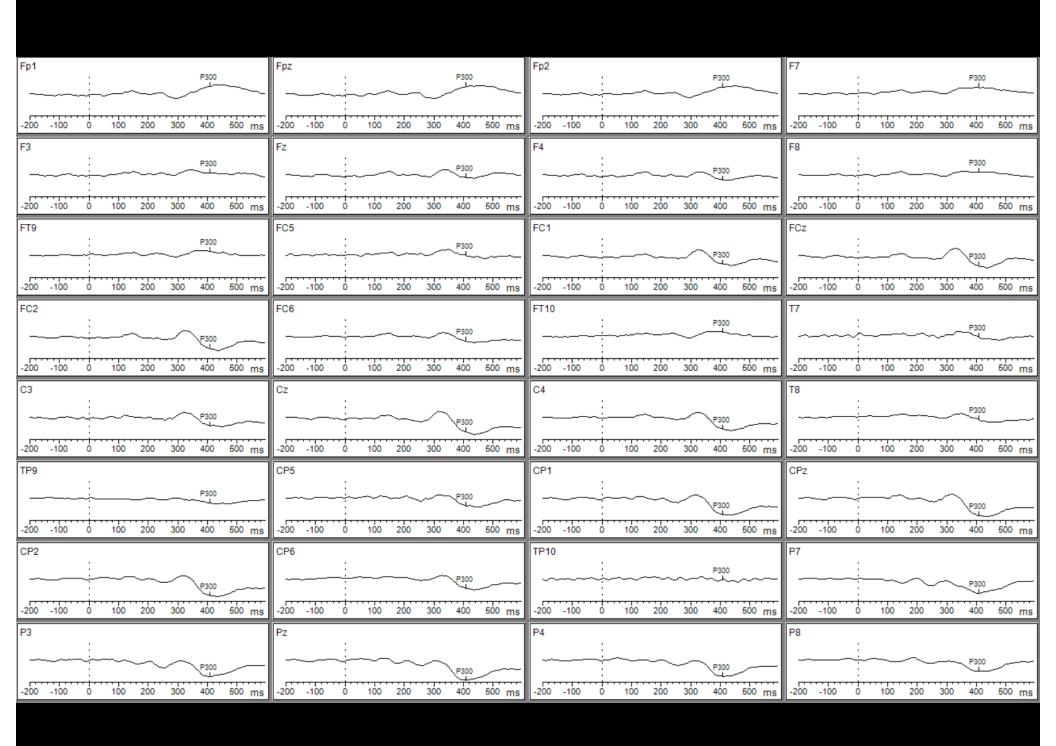
If you are going to use maximum or minimum values in your search, it is important to search on a specific channel based on the topography of the grand average waveform and/or previous literature.

Example:

I want to find the maxima (or minima) on channel Pz

At that point in time, get the voltages for all other channels

Generate a "peak topography" that is the mean of the individual peak topographies (MATLAB or EXCEL)





Again, you always want to get the voltages with respect to a peak reference channel. IE, in a maxima and minima search you define the reference channel and get all the peaks at this point in time.

Statistics

Peak Statistics

If you are using conditional waveforms:

Paired Samples T-Tests

ANOVA

If you are using difference waveforms:

Single Sample T-Tests

Paired Samples T-Tests

ANOVA

 Don't do them. Simply report a maximum (or minimum literature), show a picture, and hopefully cite a similarity with the literature.

2. T-Test

Lets say you hypothesize that the N200 is maximal at FCz, but the P300 is maximal at Pz.

Get the peak values at FCz and Pz for the N200 at the same time and t-test them.

Hypothesis, FCz > Pz

Repeat for the P300.

Hypothesis, Pz > FCz

3. Create a 3 x 3 grid of electrodes.

F3	Fz	F4
C 3	Cz	C4
Р3	Pz	P4

RM ANOVA: 3 (laterality) x 3 (azimuth) design

More complex

RM ANOVA: 3 (laterality) x 3 (azimuth) x 2 condition design

I'm always amazed when this actually works...

4. Trend Analysis

Two separate ANOVAs

T7 C3 Cz C4 T8

Fpz Fz FCz Cz CPz Pz POz Oz

Look for linear or quadratic trends

